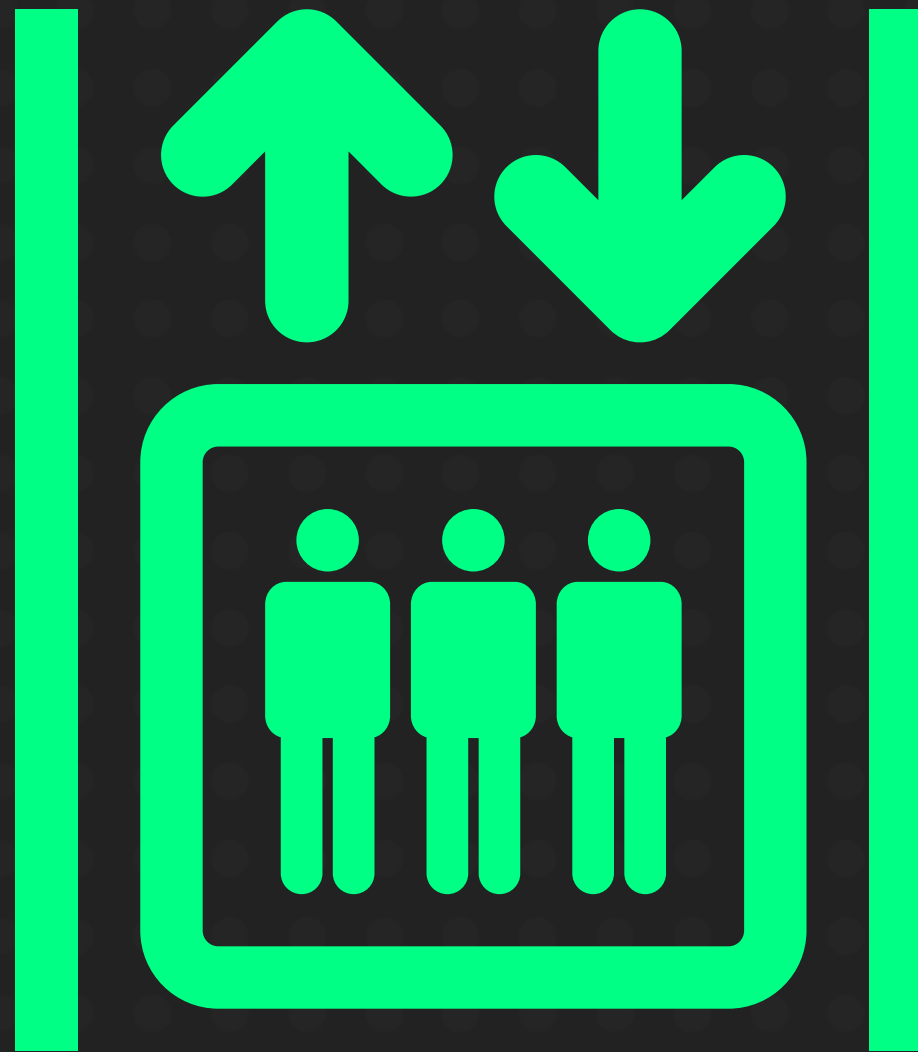
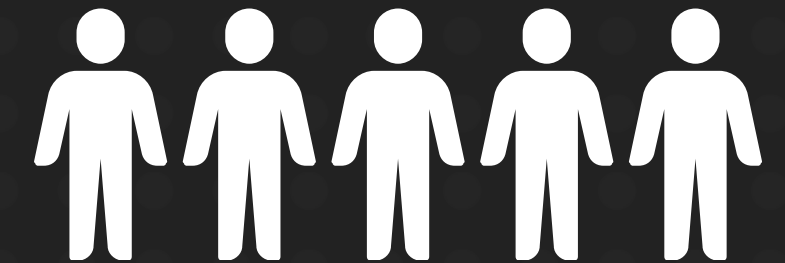


IPC-2011

ELEVATOR SEQUENTIAL OPTIMAL

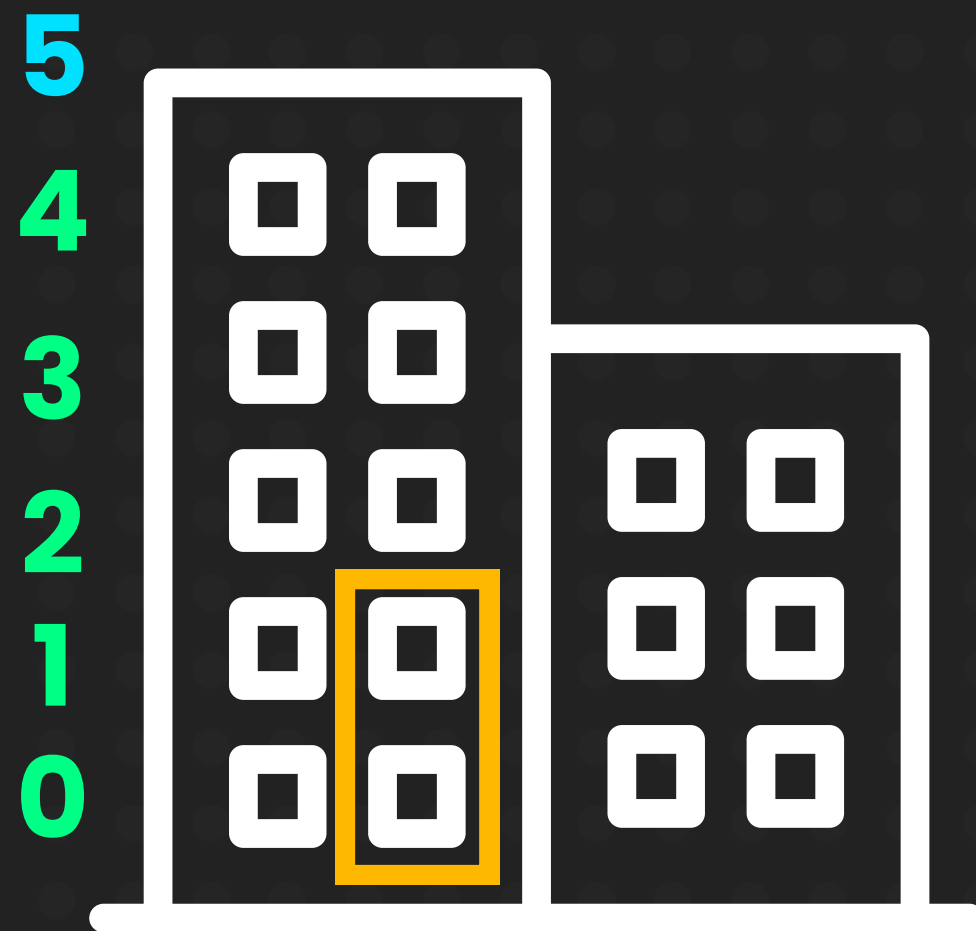


ABRIL / 9



FUNDAMENTOS LÓGICOS
DE INTELIGÊNCIA
ARTIFICIAL

Sobre o problema



Há um prédio com $N + 1$ andares, numerados de 0 a N .

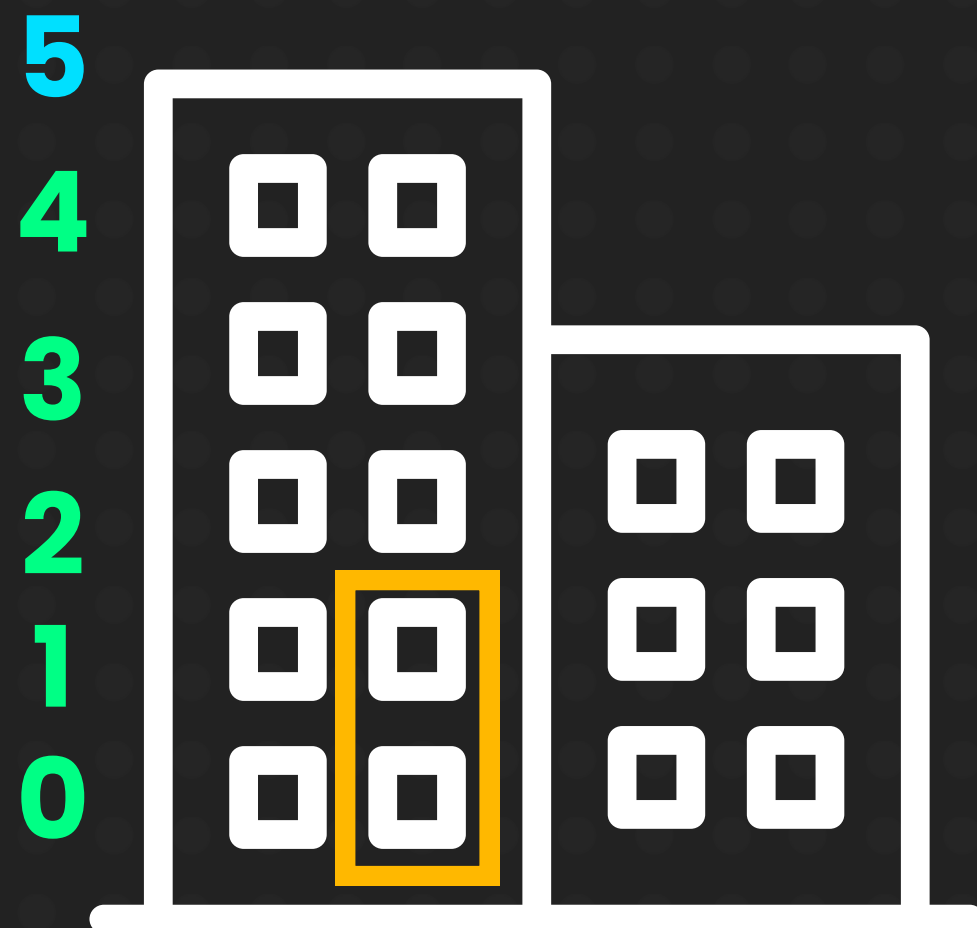
O prédio pode ser dividido em blocos de tamanho M , onde M divide N

Exemplo:

$$N = 4$$

$$M = 2$$

Sobre o problema



Blocos adjacentes têm um andar em comum.

Por exemplo, suponha que $N = 12$ e $M = 4$, então temos um total de **13** andares (**variando de 0 a 12**), que formam **3 blocos** de **5 andares** cada, sendo **0 a 4**, **4 a 8** e **8 a 12**.

Sobre o problema

O prédio possui K elevadores **rápidos** (acelerados) que **param apenas em andares que são múltiplos de $M / 2$**

M deve ser um número par!

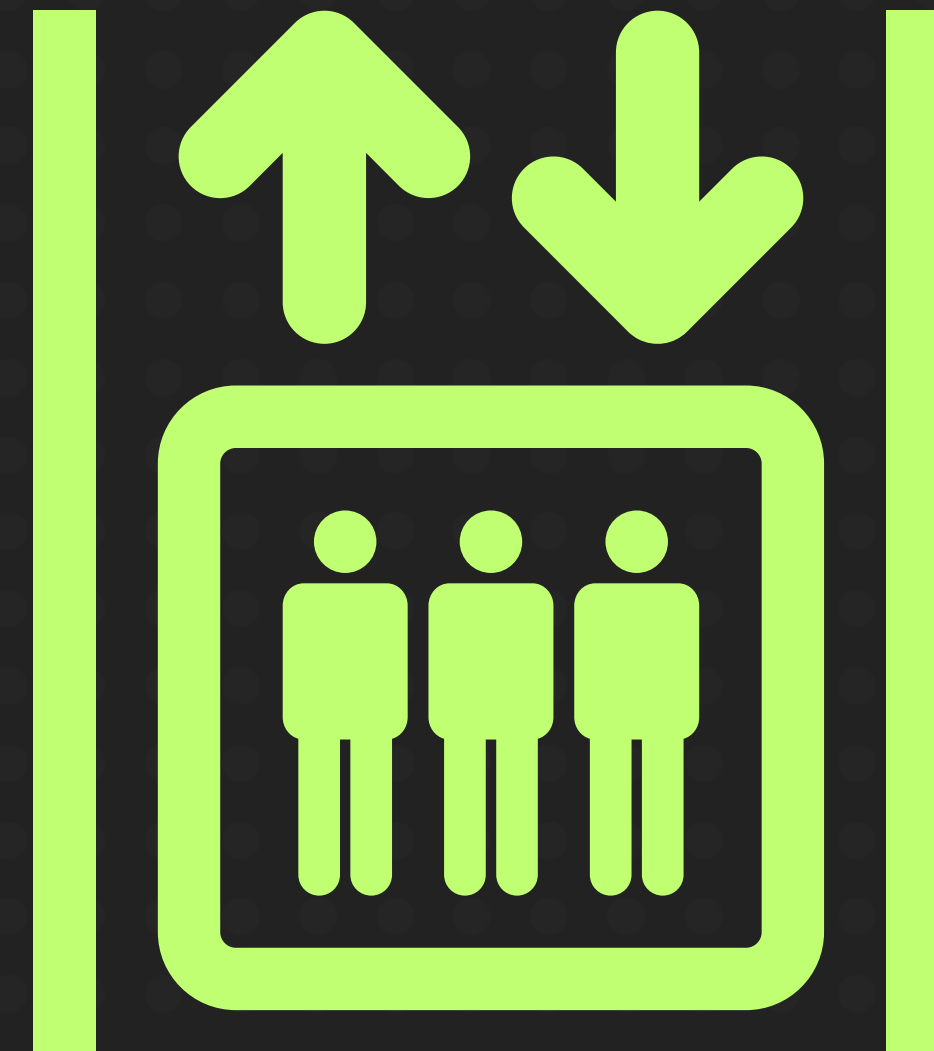
O elevador **rápido** tem capacidade para **X** pessoas



Sobre o problema

Dentro de cada **bloco**, há L **elevadores lentos**, que param em cada andar do bloco.

O elevador **lento** tem capacidade para Y pessoas



Requirements e Types

```
(:requirements :typing :action-costs)
(:types        elevator - object
              slow-elevator fast-elevator - elevator
              passenger - object
              count - object
)
```

Predicados

```
(:predicates
  (passenger-at ?person - passenger ?floor - count)
  (boarded ?person - passenger ?lift - elevator)
  (lift-at ?lift - elevator ?floor - count)
  (reachable-floor ?lift - elevator ?floor - count)
  (above ?floor1 - count ?floor2 - count)
  (passengers ?lift - elevator ?n - count)
  (can-hold ?lift - elevator ?n - count)
  (next ?n1 - count ?n2 - count)
)
```

Predicados

(passenger-at ?person – passenger ?floor – count)

faz referencia/seta qual andar o passageiro está

(boarded ?person – passenger ?lift – elevator)

coloca uma pessoa **p** em um elevador **lift**

(lift-at ?lift – elevator ?floor – count)

mover os elevador entre os andares

Predicados

(reachable-floor ?lift – elevator ?floor – count)

marca em quais andares cada elevador pode ir

(above ?floor1 – count ?floor2 – count)

marca se **n1** está abaixo de **n2**

(passengers ?lift – elevator ?n – count)

quantos passageiros tem no elevador

Predicados

(can-hold ?lift – elevator ?n – count)

quantos passageiros um elevador pode levar

(next ?n1 – count ?n2 – count)

determina a ordem nos numeros, de **n1** até **nn**

Funções

```
(:functions (total-cost) - number  
  (travel-slow ?f1 - count ?f2 - count) - number  
  (travel-fast ?f1 - count ?f2 - count) - number  
)
```

Funções

functions (total-cost) – number

Representa o custo total ao longo do planejamento

(travel-slow ?f1 – count ?f2 – count) – number

Custo de uma viagem entre andares de um elevador lento

recebe os parâmetros f1 e f2 ,que são os andares de inicio e de termino da viagem, respectivamente e retorna o custo da viagem

Funções

(travel-fast ?f1 – count ?f2 – count) – number

Custo de uma viagem entre andares de um elevador rápido

recebe os parâmetros f1 e f2 ,que são os andares de inicio e de termino da viagem, respectivamente e retorna o custo da viagem

Funções

ARQUIVO DE PROBLEMA Custo das ações

```
(= (travel-fast n0 n3) 10) (= (travel-fast n0 n6) 19) (= (travel-fast n0 n9) 19) (= (travel-fast n0 n12) 19) (= (travel-fast n3 n6) 10) (= (travel-fast n3 n9) 19) (= (travel-fast n3 n12) 19) (= (travel-fast n6 n9) 10) (= (travel-fast n6 n12) 19) (= (travel-fast n9 n12) 10) (= (total-cost) 0)
```

Actions

(:action move-up-slow

:parameters (?lift – slow-elevator ?f1 – count ?f2 – count)

:precondition (and (lift-at ?lift ?f1) (above ?f1 ?f2) (reachable-floor ?lift ?f2))

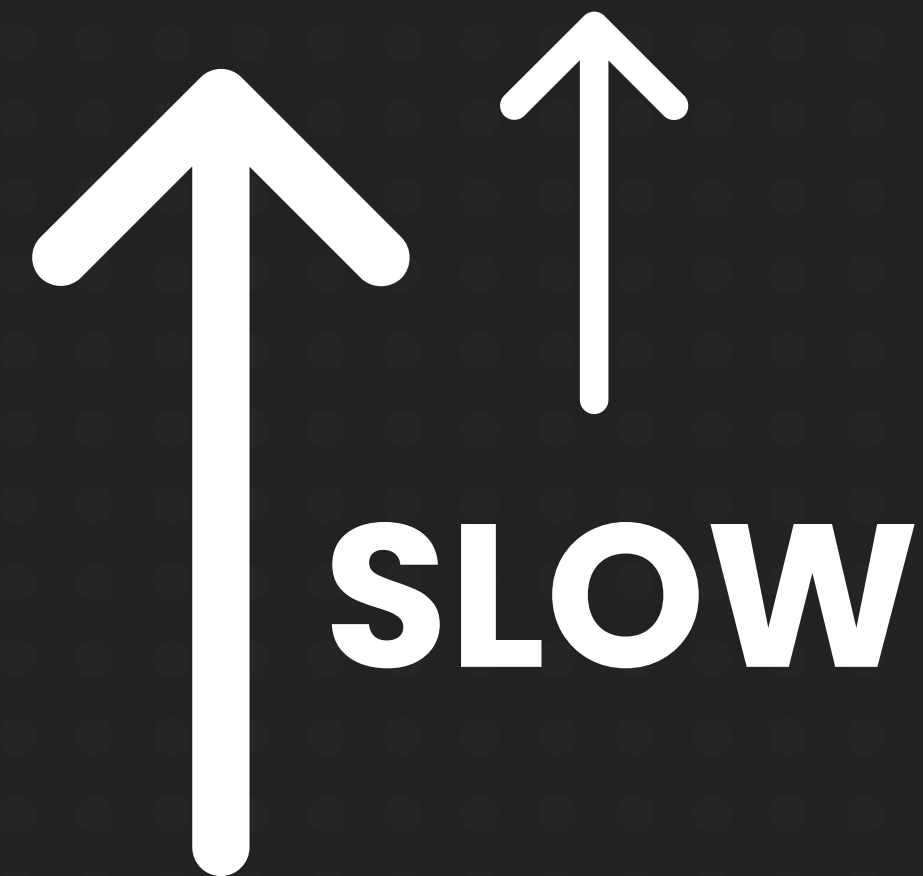
:effect (and

(lift-at ?lift ?f2)

(not (lift-at ?lift ?f1))

(increase (total-cost)

(travel-slow ?f1 ?f2))))



Actions

(:action move-down-slow

:parameters (?lift - slow-elevator ?f1 - count ?f2 - count)

:precondition (and (lift-at ?lift ?f1) (above ?f2 ?f1) (reachable-floor ?lift ?f2))

:effect (and

(lift-at ?lift ?f2)

(not (lift-at ?lift ?f1))

(increase (total-cost)

(travel-slow ?f2 ?f1))))

diferença do travel-slow e above



Actions

(:action move-up-fast

:parameters (?lift – slow-elevator ?f1 – count ?f2 – count)

:precondition (and (lift-at ?lift ?f1) (above ?f1 ?f2) (reachable-floor ?lift ?f2))

:effect (and

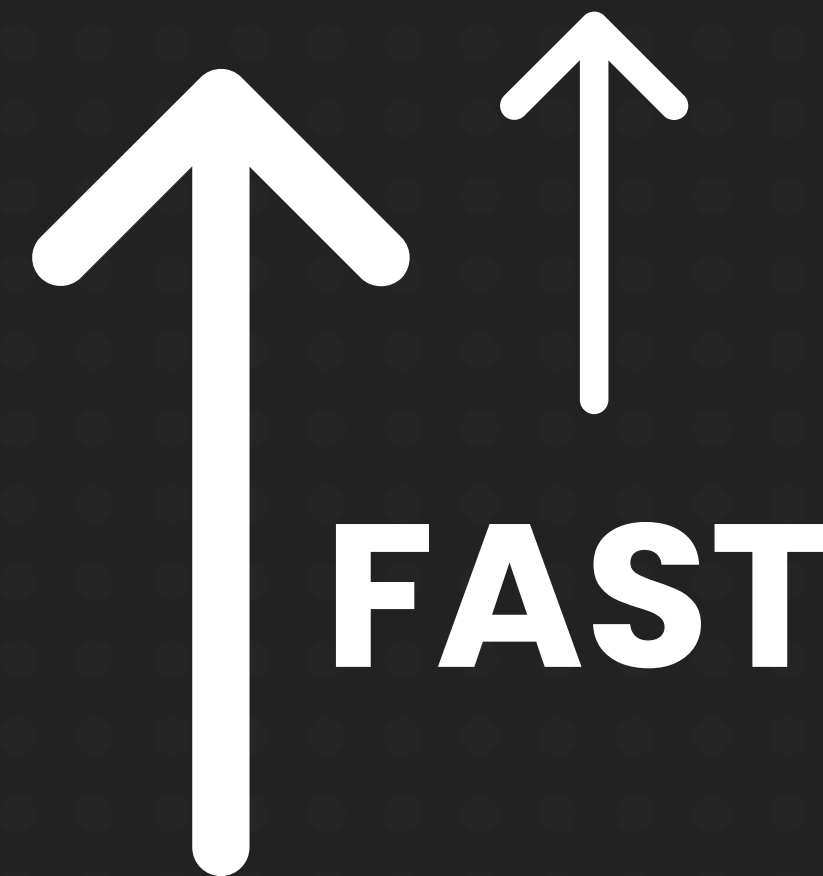
(lift-at ?lift ?f2)

(not (lift-at ?lift ?f1))

(increase (total-cost)

(travel-slow ?f1 ?f2))))

igual ao slow



Actions

(:action move-down-fast

:parameters (?lift - slow-elevator ?f1 - count ?f2 - count)

:precondition (and (lift-at ?lift ?f1) (above ?f2 ?f1) (reachable-floor ?lift ?f2))

:effect (and

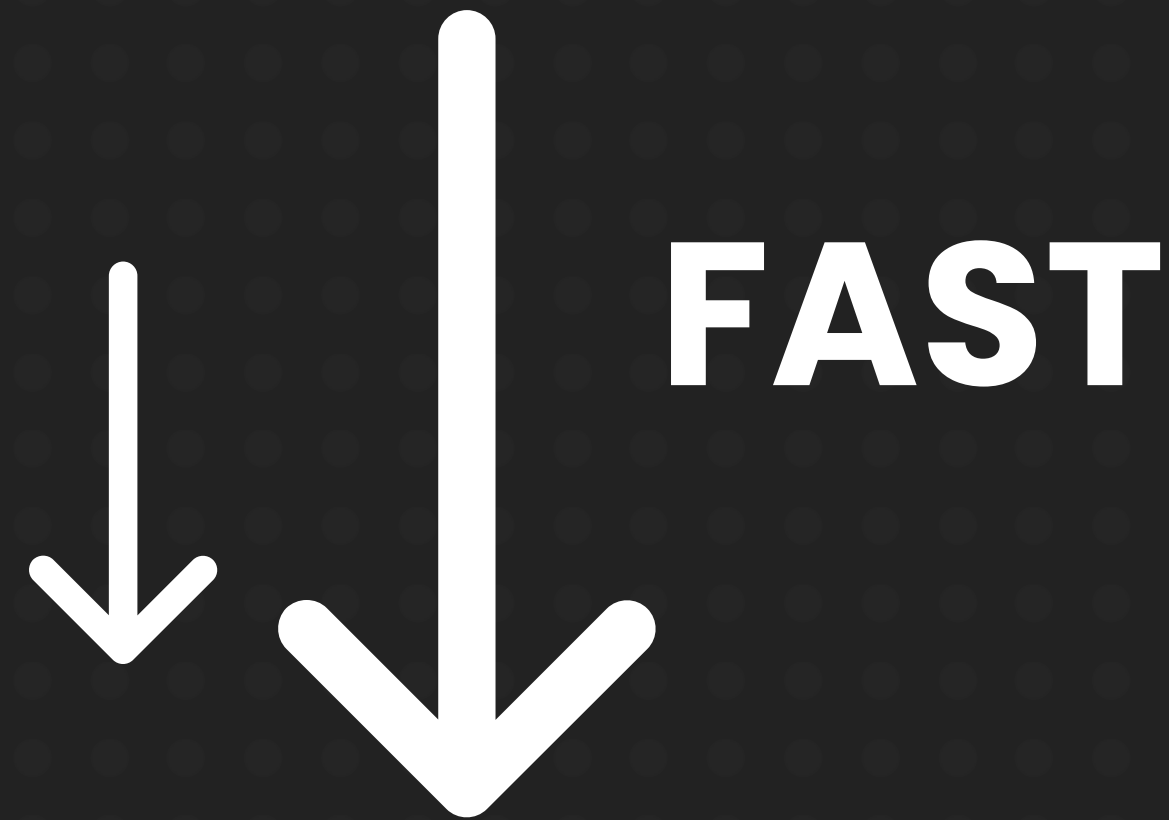
(lift-at ?lift ?f2)

(not (lift-at ?lift ?f1))

(increase (total-cost)

(travel-slow ?f2 ?f1))))

igual ao slow também!



Actions

(:action board

:parameters (?p – passenger ?lift – elevator ?f – count ?n1 – count ?n2 – count)

:precondition (and

(lift-at ?lift ?f)

(passenger-at ?p ?f)

(passengers ?lift ?n1)

(next ?n1 ?n2)

(can-hold ?lift ?n2))

:effect (and

(not (passenger-at ?p ?f)

(boarded ?p ?lift)

(not (passengers ?lift ?n1))

(passengers ?lift ?n2)))

N1 e N2 fazem referência a quantidade de pessoas no elevador.

N1 quantidade atual

N2 quantos vai ter



Actions

(:action leave

:parameters (?p – passenger ?lift – elevator ?f – count ?n1 – count ?n2 – count)

:precondition (and

(lift-at ?lift ?f)

(boarded ?p ?lift)

(passengers ?lift ?n1)

(next ?n2 ?n1))

:effect (and

(passenger-at ?p ?f)

(not (boarded ?p ?lift))

(not (passengers ?lift ?n1))

(passengers ?lift ?n2)))



Resultado

Julia FF

```
(move-down-slow slow1-0 n8 n7)
(move-down-slow slow0-0 n6 n0)
(board p0 slow0-0 n0 n0 n1)
(board p1 slow0-0 n0 n1 n2)
(move-up-slow slow0-0 n0 n3)
(leave p0 slow0-0 n3 n2 n1)
(move-down-slow slow0-0 n3 n2)
(move-down-slow slow1-0 n7 n6)
(board p2 slow0-0 n2 n1 n2)
(move-up-slow slow0-0 n2 n6)
(leave p1 slow0-0 n6 n2 n1)
(leave p2 slow0-0 n6 n1 n0)
(board p2 slow1-0 n6 n0 n1)
(board p1 slow1-0 n6 n1 n2)
(move-up-slow slow1-0 n6 n7)
(leave p2 slow1-0 n7 n2 n1)
(move-up-slow slow1-0 n7 n11)
(leave p1 slow1-0 n11 n1 n0)
```

Referências

<https://github.com/potassco/pddl-instances>

<https://planning.wiki/ref>

Getting Started With Automated Planning – Dominik
Schreiber

MUITO OBRIGADO!

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